

Fig. 2: Evolution of the blocking rate after $n \in \{1, 2, 3\}$ setup attempts.

BER is derived. In both cases, if the derived BER is acceptable, s starts signaling along p , otherwise another path is computed and tentatively established. During the signaling session, link resources (i.e., a wavelength along p) are reserved and optical crossconnects configured. To verify the lightpath QoT is acceptable, probing is performed and QoT measurements are gathered at d , which sends the measured values back towards s . Each node along p fills its proper MD entry with the updated end-to-end measurements. Note that the QoT measurements are not flooded by OSPF-TE in the network, to keep the scheme scalable. If the measured parameters indicate an unacceptable QoT for p , s frees resources along p and performs another setup attempt. Otherwise, the lightpath is activated and data transmission begins.

Simulation Results

The performance of the proposed scheme is evaluated for a Pan-European topology with 17 nodes, 32 bidirectional links, and 40 wavelengths per direction. To benchmark NKS, we disable the network kriging estimation step and call *measurement database based scheme* (MDS) this new establishment technique, which uses the information contained in MD without exploiting Network Kriging. Lightpath requests are uniformly distributed among all node pairs, following a Poisson process with mean inter-arrival time $1/\lambda$, and holding times are exponentially distributed with a mean $1/\mu$. The offered network load in Erlang is λ/μ . $P_{s,d}$ is the set of all paths connecting s and d that are within one hop from the shortest path and wavelength assignment is first fit. NKS and MDS are compared in terms of blocking rate after a variable number of setup attempts n : blocking occurs if no wavelength can be found on any path of $P(s, d)$ or if the monitored QoT parameters (using probing, after establishment) indicate unacceptable lightpath QoT.

Fig. 2 shows the blocking rate of NKS and MDS for a fixed load (200 Erlang, low enough such that blocking is due to QoT only) after $n \in \{1, 2, 3\}$ setup attempts along alternate routes measured after a varying number of lightpath requests. The plotted results

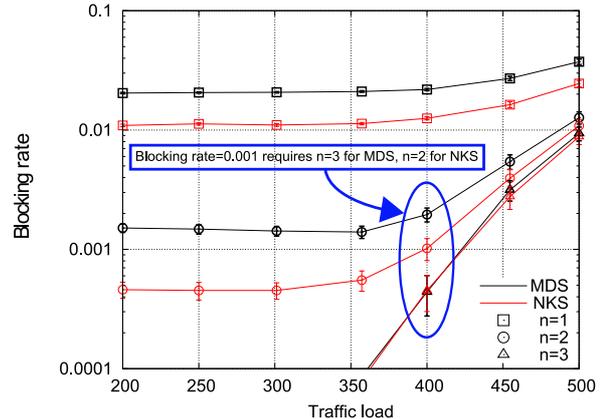


Fig. 3: Blocking rate after $n \in \{1, 2, 3\}$ setup attempts for a varying load.

are obtained by averaging 100 randomly generated sequences of lightpath requests and blocking rate is computed for a sliding window containing the last 100 requests. In both NKS and MDS, as the MD is populated, more information is gathered and the blocking rate decreases with lightpaths demands. Convergence is faster for NKS, which is able to better exploit than MDS the information in the MD. For instance, if a single establishment attempt is considered, MDS achieves a 1%-blocking rate after the arrival of 1200 lightpaths, twice as many as with NKS.

In Fig. 3, we show the lightpath blocking rate for a varying traffic load after $n \in \{1, 2, 3\}$ setup attempts. Each point is obtained by averaging 100 independent trials of 1500 lightpath requests each. In the range [200,300] Erlang, blocking probability is constant for $n \in \{1, 2\}$ because within 1500 requests, the MD is not completely filled in case of MDS, or, in the case of NKS, network kriging does not have enough information to provide confident estimations for every (s, d) pairs. For low and medium loads, if a target blocking rate of 10^{-3} is set, 3 setup attempts for each lightpath arrival are required by MDS while NKS needs only 2.

In conclusion, we harnessed the “network kriging” estimation framework to estimate lightpaths’ QoT before establishment based on prior measurements and using the correlation between lightpaths’ QoT induced by the network topology. Simulation results show that with network kriging, fewer attempts are required to successfully establish lightpaths.

Acknowledgement

The work described in this paper was carried out with the support of the BONE project (“Building the Future Optical Network in Europe”), a Network of Excellence funded by the European Commission through the 7th ICT-Framework Programme and DICONET projects.

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